

SB 14.10.2008

$$(Dg)_{\mu\nu} = dg_{\mu\nu} - \Gamma_{\mu\nu} - \Gamma_{\nu\mu}$$

$$\Rightarrow \boxed{(\Gamma_{\mu\nu\lambda} + \Gamma_{\nu\mu\lambda})\theta^\lambda = dg_{\mu\nu} - (Dg)_{\mu\nu}}$$

$$d\theta^\mu + \Gamma^\mu_{\nu\lambda}\theta^\nu\theta^\lambda = \Theta^\mu$$

$$d\theta^\lambda = -\frac{1}{2}C^\lambda_{\nu\sigma}\theta^\nu\theta^\sigma$$

$$\Gamma_{\mu\nu\lambda}\theta^\lambda\theta^\nu = \Theta_\mu + \frac{1}{2}C_{\mu\nu\sigma}\theta^\nu\theta^\sigma$$

 $X_\nu \lrcorner X_\sigma \lrcorner :$

$$\Theta_\mu = \frac{1}{2}Q_{\mu\nu\sigma}\theta^\nu\theta^\sigma$$

$$(2) \quad \Gamma_{\mu\nu\sigma} - \Gamma_{\sigma\nu\mu} = -Q_{\mu\nu\sigma} - C_{\mu\nu\sigma}$$

$$(Dg)_{\mu\nu} = 0$$

$$(1) \quad \Gamma_{\nu\mu\sigma} + \Gamma_{\mu\nu\sigma} = g_{\nu\mu\sigma}$$

$$df = f_{|\sigma}\theta^\sigma = X_\sigma(f)\theta^\sigma$$

$$(1) - (2) \quad \Gamma_{\nu\mu\sigma} + \Gamma_{\mu\sigma\nu} = g_{\nu\mu\sigma} + Q_{\mu\nu\sigma} + C_{\mu\nu\sigma} = H_{\nu\mu\sigma}$$

$$\boxed{H_{\nu\mu\sigma} = g_{\nu\mu\sigma} + Q_{\mu\nu\sigma} + C_{\mu\nu\sigma}}$$

+	$\Gamma_{\nu\mu\sigma} + \Gamma_{\mu\sigma\nu} = H_{\nu\mu\sigma}$
+	$\Gamma_{\sigma\nu\mu} + \Gamma_{\nu\mu\sigma} = H_{\sigma\nu\mu}$
-	$\Gamma_{\mu\sigma\nu} + \Gamma_{\sigma\nu\mu} = H_{\mu\sigma\nu}$

$$H_{\nu\mu\sigma} = g_{\nu\mu\sigma} + Q_{\nu\sigma\mu} + C_{\nu\sigma\mu}$$

$$H_{\sigma\nu\mu} = g_{\sigma\nu\mu} + Q_{\sigma\mu\nu} + C_{\sigma\mu\nu}$$

$$2\Gamma_{\nu\mu\sigma} = H_{\nu\mu\sigma} + H_{\sigma\nu\mu} - H_{\mu\sigma\nu}$$

$$\Gamma_{r\mu s} = \frac{1}{2} (g_{r\mu s} + g_{s\mu r} - g_{\mu sr} + \\ + C_{\mu rs} + C_{r\mu s} - C_{s\mu r} + \\ + Q_{\mu rs} + Q_{r\mu s} - Q_{s\mu r})$$

Given a torsion $\Theta^s = \frac{1}{2} Q^s_{\mu\nu} \theta^\mu \wedge \theta^\nu$ there is a UNIQUE connection ∇ s.t. it has Θ^s as a torsion form and which satisfies $Dg_{\mu\nu} = 0$.

(Extend this then to $Dg_{\mu\nu} = B_{\mu\nu}$ - given 1-form of type $\binom{0}{2}$)

Assumption

No Torsion: $Q \equiv 0$

LEVI-CIVITA CONNECTION

① Coordinate frame $X_\mu = \frac{\partial}{\partial x^\mu}$, $[X_\mu, X_\nu] = 0$
 $\Rightarrow C_{\mu\nu s} \equiv 0$

$$\Rightarrow \Gamma_{r\mu s} = \frac{1}{2} (g_{r\mu, s} + g_{s\mu, r} - g_{\mu sr})$$

$$\Rightarrow \Gamma^r_{\mu s} = g^{ra} \Gamma_{a\mu s} =: \left\{ \begin{matrix} r \\ \mu s \end{matrix} \right\} \leftarrow \text{Christoffel symbols}$$

②

$$g_{\mu\nu} = (\text{const})_{\mu\nu}$$

e.g. Orthonormal frame

$$g_{\mu\nu} = \pm \delta_{\mu\nu}$$

$$\Rightarrow \boxed{\Gamma_{\nu\mu\sigma} = \frac{1}{2} (C_{\mu\nu\sigma} + C_{\nu\sigma\mu} - C_{\sigma\mu\nu})}$$

↑
in an orthonormal frame (or other frame in which $g_{\mu\nu} = \text{const}_{\mu\nu}$) $\Gamma_{\nu\mu\sigma}$ are determined by the anholonomy coefficients.

Note

$$\begin{cases} d\theta^\mu + \Gamma^\mu_{\nu\lambda} \theta^\nu = 0 \\ dg_{\mu\nu} + \Gamma_{\mu\nu} - \Gamma_{\nu\mu} = 0 \end{cases}$$

↙ No Torsion

in the orthonormal (or constant coefficient frame)
we have

$$\begin{cases} d\theta^\mu + \Gamma^\mu_{\nu\lambda} \theta^\nu = 0 \\ \Gamma_{\mu\nu} + \Gamma_{\nu\mu} = 0 \end{cases}$$

← These determine connection.

Arc length

$$t \rightarrow \gamma(t), \quad \dot{\gamma} = \frac{d\gamma}{dt}$$

$$s := \int_{t_0}^t \sqrt{g(\dot{\gamma}, \dot{\gamma})} dt$$

$$t \rightarrow t' = f(t), \quad f' > 0 \Rightarrow s \text{ does not change.}$$

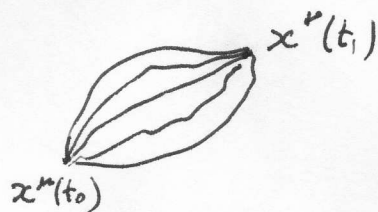
$$s \text{ is itself a good parameter: } \frac{ds}{dt} = \sqrt{g(\dot{\gamma}, \dot{\gamma})} > 0$$

Def

γ of class C^2 is a geodesic iff it is a critical point for the functional

$$\gamma \mapsto s[\gamma]$$

Locally



$$\delta \int_{t_0}^t \sqrt{g_{\mu\nu} \frac{dx^\mu}{dt} \frac{dx^\nu}{dt}} dt = 0$$

$$\begin{aligned} \delta x^\mu(t_0) &= 0 \\ \delta x^\nu(t_1) &= 0 \end{aligned}$$

Euler-Lagrange equations:

$$\frac{d}{dt} \frac{\partial}{\partial \dot{x}^\mu} \sqrt{g_{\mu\nu} \dot{x}^\mu \dot{x}^\nu} - \frac{\partial}{\partial x^\mu} \sqrt{g_{\mu\nu} \dot{x}^\mu \dot{x}^\nu} = 0$$

$$\frac{d}{dt} \frac{g_{\mu\nu} \dot{x}^\nu}{\sqrt{g_{\mu\nu} \dot{x}^\mu \dot{x}^\nu}} - \frac{1}{2} \frac{g_{\nu s, \mu} \dot{x}^\nu \dot{x}^s}{\sqrt{g_{\mu\nu} \dot{x}^\mu \dot{x}^\nu}} = 0 \quad | : \sqrt{\quad}$$

$$\frac{d}{ds} = \frac{d}{dt} \frac{dt}{ds}$$

$$\frac{d}{ds} g_{\mu\nu} \frac{dx^\nu}{ds} - \frac{1}{2} g_{\nu s, \mu} \frac{dx^\nu}{ds} \frac{dx^s}{ds} = 0$$

$$g_{\mu\nu} \frac{d^2 x^\nu}{ds^2} + \underbrace{\left(g_{\mu\nu,s} - \frac{1}{2} g_{rs,\mu} \right)}_{\parallel} \frac{dx^\nu}{ds} \frac{dx^s}{ds} = 0$$

$$\frac{1}{2} (g_{\mu\nu,s} + g_{s\mu,\nu})$$

$$\frac{d^2 x^\sigma}{ds^2} + \frac{1}{2} g^{\sigma\mu} (g_{\mu\nu,s} + g_{s\mu,\nu} - g_{rs,\mu}) \frac{dx^\nu}{ds} \frac{dx^s}{ds} = 0$$

$$\boxed{\frac{d^2 x^\sigma}{ds^2} + \left\{ \begin{matrix} \sigma \\ \nu s \end{matrix} \right\} \frac{dx^\nu}{ds} \frac{dx^s}{ds} = 0}$$

↑ christoffel symbols

Corollary

Geodesics $\equiv$ self parallels for the Levi-Civita connection in affine parametrization.

What about pseudoriemannian situation?

for null vectors X $s=0$!

Energy functional

$$E[X] = \frac{1}{2} \int_{t_0}^t g(X, X) dt = \int_{t_0}^t g_{\mu\nu} \dot{x}^\mu \dot{x}^\nu dt$$

↑
does depend on parametrization

$$\delta E = 0$$

$$\frac{1}{2} \frac{d}{dt} \frac{\partial}{\partial \dot{x}^\mu} g_{\mu\nu} \dot{x}^\mu \dot{x}^\nu - \frac{1}{2} \frac{\partial}{\partial x^\mu} g_{\mu\nu} \dot{x}^\mu \dot{x}^\nu = 0$$

$$\frac{d}{dt} g_{\mu\nu} \dot{x}^\nu - \frac{1}{2} g_{\mu\sigma, \lambda} \dot{x}^\sigma \dot{x}^\lambda = 0$$

$$g_{\mu\nu} \ddot{x}^\nu + (g_{\mu\nu, \lambda} - \frac{1}{2} g_{\lambda\sigma, \mu}) \dot{x}^\sigma \dot{x}^\lambda = 0$$

$$\boxed{\frac{d^2 x^\sigma}{dt^2} + \{\sigma\}_{rs} \dot{x}^r \dot{x}^s = 0}$$

- 1) in this parametrization we again get geodesic equation with t as an affine parameter.
- 2) derivation is also good for $\frac{ds}{dt} = X$ s.t. $g(X, X) = 0$.